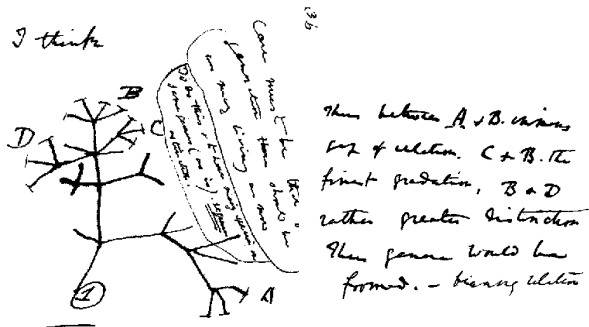
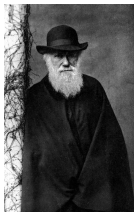


# Bioinformatics

## (Phylogenetic Tree Reconstruction)

Marc Hellmuth

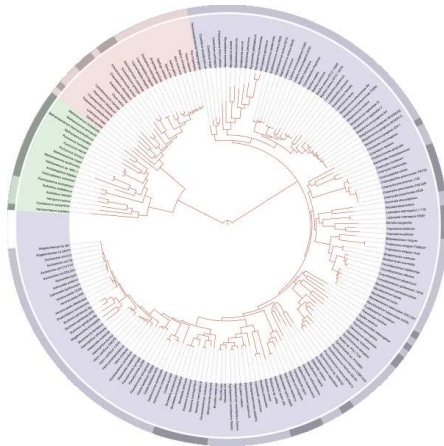


"I think" by Charles Darwin (1837) - One of the first evolutionary trees.

## Ernst Haeckel, 1879

# Tree of Life - A Better Picture<sup>1</sup>

Relationship between species with sequenced genomes as of 2006.



center = last universal ancestor of all life on earth.

three domains of life:

eukaryota (animals, plants and fungi);

bacteria;

archaea.

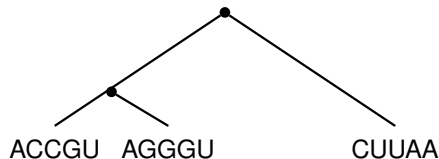
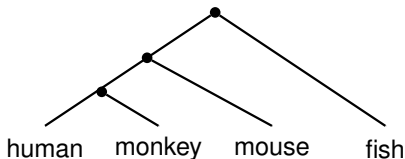
<sup>1</sup> Ciccarelli, FD (2006). "Toward automatic reconstruction of a highly resolved tree of life.". Science; Letunic, I (2007). "Interactive Tree Of Life (iTOL): an online tool for phylogenetic tree display and annotation.". Bioinformatics



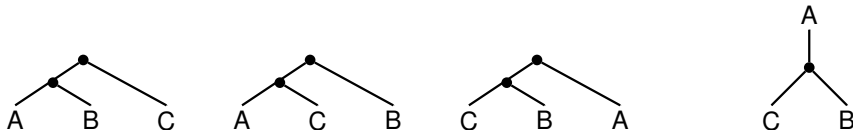
**Aim:** Assemble a tree representing a hypothesis about the evolutionary history of a set of genes, species or other taxa.

Trees are "good" approximation (does not work if one considers e.g. horizontal gene transfers)

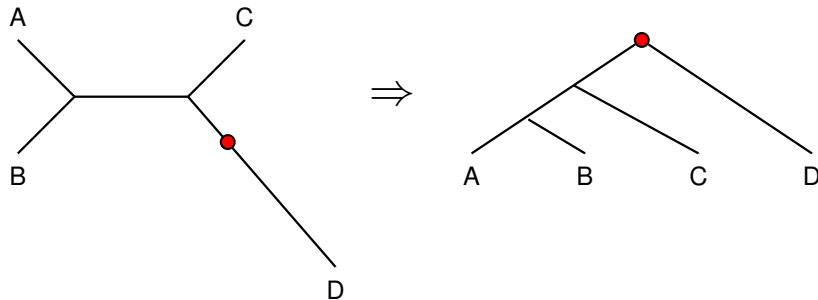
A **phylogenetic tree on set of taxa  $X$**  is tuple  $(T, \lambda)$  s.t.  $T = (V, E)$  is unordered tree with unique labels  $\lambda(v) \in X$  for all leaves  $v \in L \subseteq V$ .



## Rooted vs. Unrooted



Unrooted tree (right) “displays” all three rooted trees on three leaves.



Depending on the application, phylogenetic trees may:

- be rooted or unrooted
- have weighted or unweighted edges
- have bounded degree  
(maximum nr of children of each internal node)

## The problem in practise:

- Inference of the gene or species tree  $T$  is a classical problem of molecular phylogenetics.  
In practice it can only be solved approximately.
- Only the subset of leaves of the species or gene tree corresponding to extant (currently living) species or genes in extant (currently living) species is observable.
- All internal nodes (and the event labeling  $t$ ) in the gene tree must be inferred from data.  
events: duplication, **speciation** (Later!)

## Lemma

*There are  $(2n-3)!! = 1 \cdot 3 \cdot \dots \cdot (2n-3)$  rooted trees with  $n$  leaves, and  $(2n-5)!!$  unrooted trees with  $n$  leaves*

$n$	3	4	5	6	10	20
Exmpl: unrooted	1	3	15	105	2'027'025	$2.22 \cdot 10^{20}$
rooted	3	15	105	945	34'459'425	$8.20 \cdot 10^{21}$

**Aim:** Assemble a tree representing a hypothesis about the evolutionary history of a set of genes, species or other taxa.

**Methods:**

- Distance Based e.g.:
  - Ultrametric Tree Reconstruction
  - Additive Tree Reconstruction
- Character Based e.g.:
  - Parsimony Methods
  - Maximum Likelihood
- Consensus Methods e.g.:
  - BUILD

# UPGMA

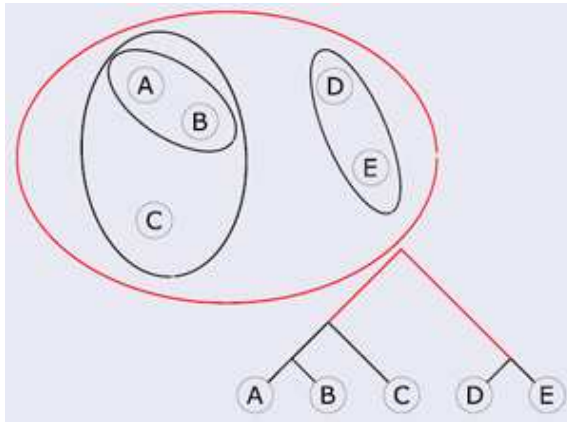
## Unweighted **P**air **G**roup **M**ethod with **A**rithmetic Mean

- Assume “constant molecular clock”:  
one assumes that mutations always appear with the same probability independent from time, location, kind of mutation (mutation = bygone past time)
- The two sequences with with the shortest evolutionary distance between them are assumed to have been the last that diverged, and represented by the most recent internal node.
- Cluster the data and at each step merge clusters.
- Distances between clusters:

$$D(C_i, C_j) = \frac{1}{|C_i||C_j|} \sum_{x \in C_i, y \in C_j} D_{x,y}$$

- Moreover, compute “ultrametric trees”.

## UPGMA - Idea

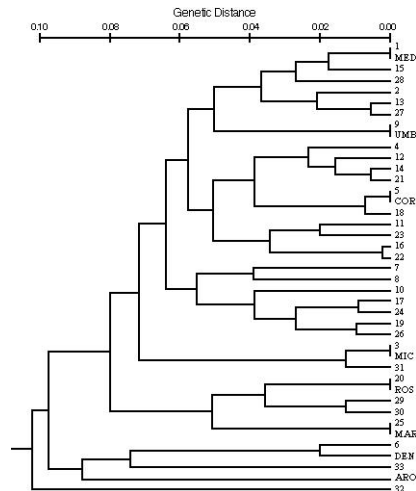


It works correctly, if the underlying “distance-matrix” is an ultrametric

A metric  $D$  on  $M = \{1, \dots, n\}$  is an ultrametric if for all  $x, y, z \in M$  holds

$$D_{xy} \leq \max\{D_{xz}, D_{zy}\}.$$

## Example: Ultrametric Tree <sup>2</sup>



<sup>2</sup>taken from: Evolution of polyploid agamic complexes with examples from *Antennaria* (Asteraceae), RJ Bayer, Opera Bot, 1996

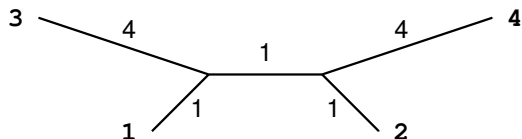


# Neighbor Joining and Additive Tree

For a given  $n \times n$  distance matrix  $D$  an additive tree  $T$  for  $D$  is an unrooted tree with

1.  $T$  is binary, having  $n$  leaves (bijectively labeled by  $1, \dots, n$ )
2. each edge  $(x, y)$  of  $T$  is (positive) weighted with branch length  $b_{xy}$
3. For any pair of leaves  $i, j$  it holds:  $D_{ij}$  = sum of edge weights  $b_{xy}$  along path from  $i$  to  $j$  in  $T$ .

$$D = \begin{pmatrix} 0 & 3 & 5 & 6 \\ & 0 & 6 & 5 \\ & & 0 & 9 \\ & & & 0 \end{pmatrix}$$

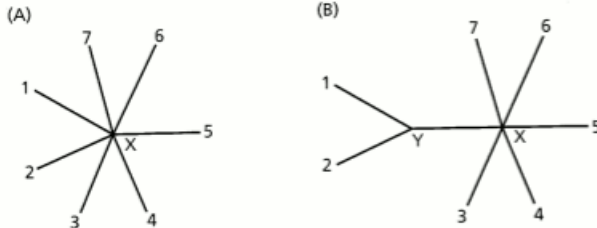


## Neighbor Joining (NJ)

NJ does not assume constant molecular clock.

Basis of NJ is concept of minimum evolution, that is, the “true” tree will be that for which the total branch length is shortest.

**Idea:** Start with “star” tree and separate stepwisely vertices that are together “quite” close and also “quite” far away from the rest until a fully resolved tree has been built. (Note, these two vertices are not necessarily the nearest ones).



It works correctly, if the underlying “distance-matrix” is additive

A metric  $D$  on  $M = \{1, \dots, n\}$  is additive if for all  $x, y, a, b \in M$  holds

$$D_{xy} + D_{ab} \leq \max\{D_{xa} + D_{yb}, D_{xb} + D_{ya}\}.$$

# Consensus Methods<sup>3</sup>

Assume a set  $T$  of phylogenetic trees has already been constructed.

Aim: Summarize the information in  $T$  in the “best way”.

“best way” := find largest subtree, find **supertree**, ...

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<sup>3</sup>parts of this section are based on talk by Jesper Jansson (2010 MSP Annual Convention)

# Supertree

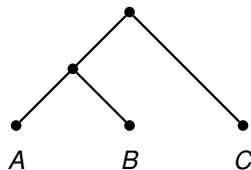
Aim: Merge a given set of (possibly conflicting) phylogenetic trees into **one** tree. Keep as much branching information as possible!

Motivation:

- Combine many trees constructed from different data sets.  
→ more reliable answers.
- Computationally expensive methods can yield highly accurate trees for small, overlapping subsets of the objects.
- Most individual studies investigate relatively few species.  
Supertrees allow us to deduce new evolutionary relationships.

# Rooted Triples

Rooted triplet= rooted binary phylogenetic tree with exactly three leaves.



For three leaves  $A, B, C$  in  $T$  we write  $((A, B), C)$  if the path from  $A$  to  $B$  does not intersect the path from  $C$  to the root  $\rho$ .

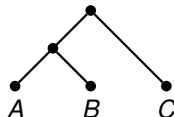
That is the unique rooted triplet with

$$lca(A, B) \prec lca(A, C) = lca(B, C)$$

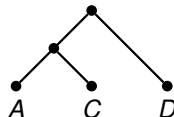
Any rooted phylogenetic tree can be represented by a set of rooted triplets.

# Combining Rooted Triples

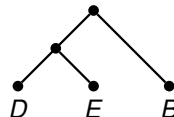
$((A, B)C)$



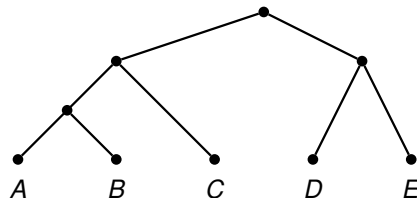
$((A, C)D)$



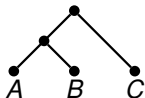
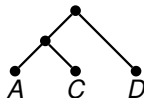
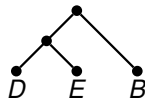
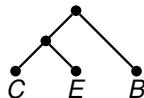
$((D, E)B)$



Consensus Tree “displays” all rooted triples:

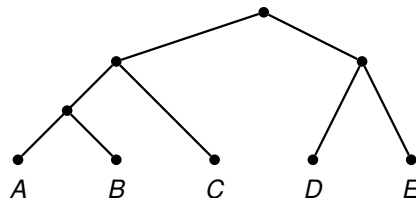


## Combining Rooted Triples

 $((A, B)C)$ 

 $((A, C)D)$ 

 $((D, E)B)$ 

 $((C, E)B)$ 


Consensus Tree does not always exist!!

# Consistency



For three leaves  $A, B, C$  in  $T$  we write  $((A, B), C)$  if the path from  $A$  to  $B$  does not intersect the path from  $C$  to the root  $\rho$ .

That is the unique rooted triplet with

$$lca(A, B) \prec lca(A, C) = lca(B, C)$$

$T$  and an arbitrary triple  $((A, B), C)$  are **consistent** iff

$$lca(A, B) \prec lca(A, C) = lca(B, C)$$

$T$  **displays**  $((A, B), C)$ .



# BUILD

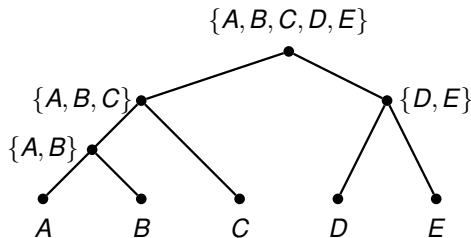
**Theorem** (Aho, Sagiv, Szymanski, Ullman - 1981; Semple & Steel - 2003)

*Let  $\mathcal{R}$  be a collection of rooted triples with leaf set  $\mathcal{L}$ . Then there is an  $O(|\mathcal{R}||\mathcal{L}|)$  time algorithm – called *BUILD* – that either*

- constructs a phylogenetic tree  $T_{|\mathcal{R}|}$  that displays each member of  $\mathcal{R}$*
- or*
- recognizes  $\mathcal{R}$  as inconsistent.*

## BUILD

**Idea of this recursive, top-down approach:** Partition  $\mathcal{L}$  into blocks according to  $\mathcal{R}$ . Output a tree consisting of a root whose children are roots of the trees obtained by recursing on each block.



## BUILD

Let  $\mathcal{R}$  be a set of triples defined on a leaf set  $\mathcal{L}$ .

For any  $L \subseteq \mathcal{L}$  define  $\mathcal{R}|_L = \{((x, y)z) \in \mathcal{R} \mid x, y, z \in L\}$ .

To find blocks use **auxiliary graph**  $G(\mathcal{R}|_L, L) = (L, E)$  with  $(x, y) \in E$  iff there is a triple  $((x, y)z) \in \mathcal{R}|_L$

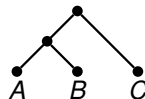
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Exmpl:  $L = \{A, B, C\}$ ,  $\mathcal{R} = ((A, B)C)$ ,  $G(\mathcal{R}|_L, L)$



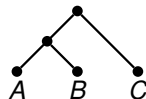
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**Exmpl:**  $L = \{A, B, C\}$ ,  $\mathcal{R} = ((A, B)C)$ ,  $G(\mathcal{R}|_L, L)$



**Crucial observation:** If  $((xy)z)$  is consistent with a tree  $T$  then the leaves labeled by  $x$  and  $y$  cannot descend from two different children of the root of  $T$ , i.e.,  $x$  and  $y$  must belong to the same block.

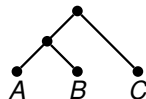
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Let  $\mathcal{R}$  be a set of triples defined on a leaf set  $\mathcal{L}$ .

For any  $L \subseteq \mathcal{L}$  define  $\mathcal{R}|_L = \{((x, y)z) \in \mathcal{R} \mid x, y, z \in L\}$ .

To find blocks use **auxiliary graph**  $G(\mathcal{R}|_L, L) = (L, E)$  with  $(x, y) \in E$  iff there is a triple  $((x, y)z) \in \mathcal{R}|_L$

**Exmpl:**  $L = \{A, B, C\}$ ,  $\mathcal{R} = ((A, B)C)$ ,  $G(\mathcal{R}|_L, L)$



**Crucial observation:** If  $((xy)z)$  is consistent with a tree  $T$  then the leaves labeled by  $x$  and  $y$  cannot descend from two different children of the root of  $T$ , i.e.,  $x$  and  $y$  must belong to the same block.

Therefore, the algorithm defines the partition of  $L \subseteq \mathcal{L}$  by:

**Blocks of leaves iff connected components in  $G(\mathcal{R}|_L, L)$**

# BUILD

Lemma (Aho, Sagiv, Szymanski, Ullman (1981), Bryant & Steel (1995))

*A given triple set  $\mathcal{R}$  on a leaf set  $\mathcal{L}$  is consistent if and only if for all  $L \subseteq \mathcal{L}$  with  $|L| > 1$  the graph  $G(\mathcal{R}|_L, L)$  is disconnected.*

## BUILD

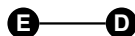
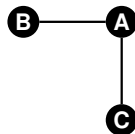
- 1: **INPUT:** Set of triples in  $\mathcal{R}$ , leaf set  $\mathcal{L}$ .
- 2: **OUTPUT:** A rooted, phylog. tree distinctly leaf-labeled by  $\mathcal{L}$  consistent with all rooted triplets in  $\mathcal{R}$ , if one exists; otherwise *null*.
- 3: compute  $G(\mathcal{R}, \mathcal{L})$
- 4: compute connected components  $C_1, \dots, C_s$  of  $G(\mathcal{R}, \mathcal{L})$
- 5: **if**  $s = 1$  and  $|\mathcal{L}| = 1$  **then**
- 6:     return tree  $\simeq K_1$
- 7: **else if**  $s = 1$  and  $|\mathcal{L}| > 1$  **then**
- 8:     return *null*
- 9: **else**
- 10:   **for**  $i = 1, \dots, s$  **do**
- 11:      $T_i = \text{BUILD}(\mathcal{R}|_{V(C_i)}, V(C_i))$
- 12:   **end for**
- 13:   **if**  $T_i \neq \text{null}$  for all  $i = 1, \dots, s$  **then**
- 14:     attach all of these trees to a common parent node and let  $T$  be the resulting tree; **else**  $T = \text{null}$ .
- 15:   **end if**
- 16: **end if**



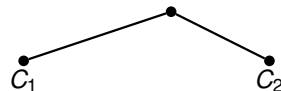
# BUILD - Example

$$\mathcal{R} = \{((AB)C), ((AC)D), ((DE)B)\}$$

$G(\mathcal{R}, \mathcal{L})$ :



$$\text{BUILD}(\mathcal{R}, \mathcal{L} = \{A, B, C, D, E\})$$



$$C_1 := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{A, B, C\})$$

$$C_2 := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{D, E\})$$

# BUILD - Example

$$\mathcal{R} = \{((AB)C), ((AC)D), ((DE)B)\}$$

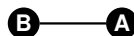
$$G_1 := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{A, B, C\})$$

$$\mathcal{R}_1 := \{((AB)C)\}$$

$$G_2 := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{D, E\})$$

$$\mathcal{R}_2 := \emptyset$$

$$G(\{A, B, C\}) :$$



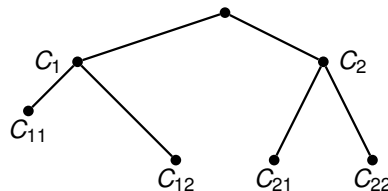
**C**

$$G(\{D, E\}) :$$

**E**

**D**

$$\text{BUILD}(\mathcal{R}, \mathcal{L} = \{A, B, C, D, E\})$$



# BUILD - Example

$$\mathcal{R} = \{((AB)C), ((AC)D), ((DE)B)\}$$

$$C_1 := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{A, B, C\})$$

$$C_2 := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{D, E\})$$

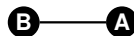
$$C_{11} := \text{BUILD}(\mathcal{R}|_{\mathcal{L}}, \mathcal{L} = \{A, B\})$$

$$C_{12} := \text{BUILD}(\emptyset, \{C\})$$

$$C_{21} := \text{BUILD}(\emptyset, \{D\})$$

$$C_{22} := \text{BUILD}(\emptyset, \{E\})$$

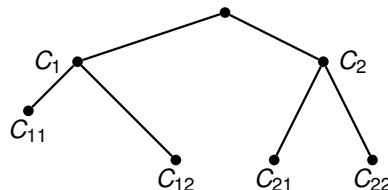
$G(\{A, B, C\}) :$



$G(\{D, E\}) :$

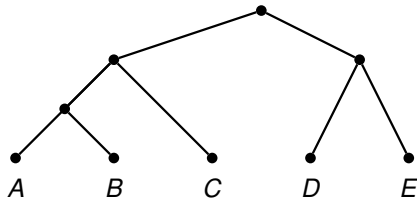


$\text{BUILD}(\mathcal{R}, \mathcal{L} = \{A, B, C, D, E\})$

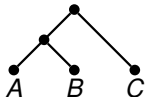
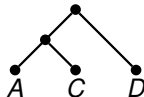
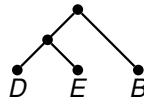
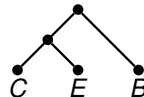


# BUILD - Example

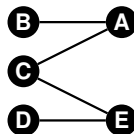
$\text{BUILD}(\mathcal{R}, \mathcal{L} = \{A, B, C, D, E\})$



# BUILD - Example

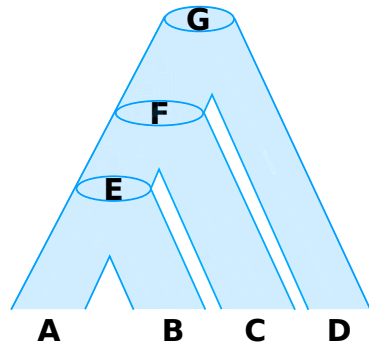
 $((A, B)C)$ 

 $((A, C)D)$ 

 $((D, E)B)$ 

 $((C, E)B)$ 


Consensus Tree does not always exist!!

 $G(\mathcal{R}, \mathcal{L}) :$ 


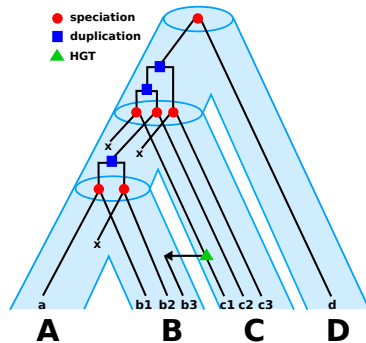
## Phylogenetics with Evolutionary Event Relations

# The “true” evolutionary History



# The “true” evolutionary History

- species are characterized by its genome:  
a “bag of genes”
- “Genes” evolve along a *rooted* tree with  
unique *event labeling*  
 $t : V^0 \rightarrow M = \{\bullet, \blacksquare, \blacktriangle\}$

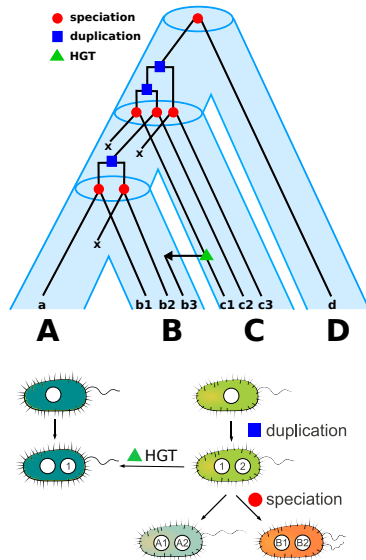




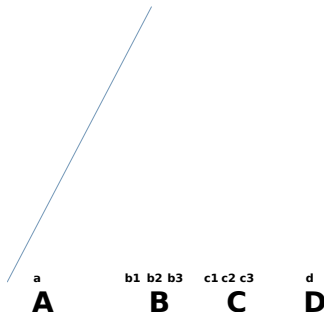
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- species are characterized by its genome:  
a “bag of genes”
- “Genes” evolve along a *rooted* tree with unique *event labeling*  
 $t : V^0 \rightarrow M = \{\bullet, \blacksquare, \blacktriangle\}$

- Gene duplication** : an offspring has two copies of a single gene of its ancestor
- Speciation** : two offspring species inherit the entire genome of their common ancestor
- HGT** : transfer of genes between organisms in a manner other than traditional reproduction and across different species

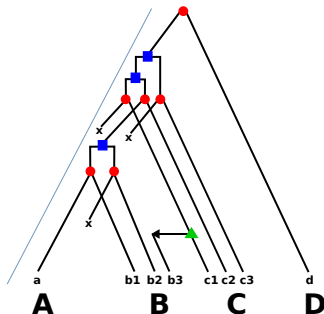


# The Problem in Practice



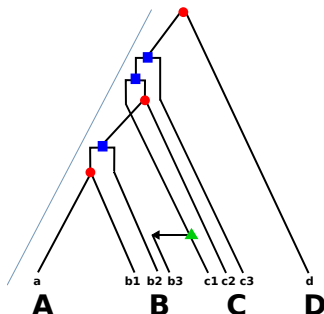
- Only the subset of leaves of the gene tree corresponding to genes in extant (currently living) species is observable.
- All internal nodes and the event labelling  $t$  in the gene tree must be inferred from data.
- We cannot observe and reconstruct all events (losses).
- The events and the topology of the gene tree can be used (under several constraints) to infer the species tree (Reconciliation)

# The Problem in Practice



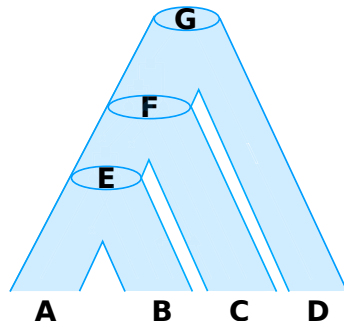
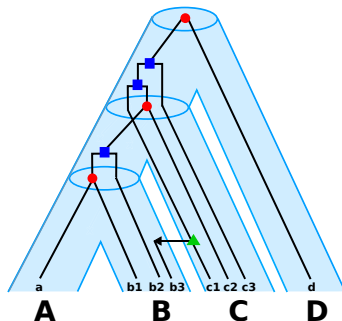
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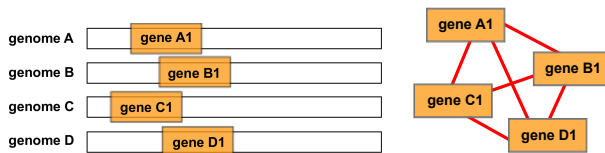
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## The Problem in Practice



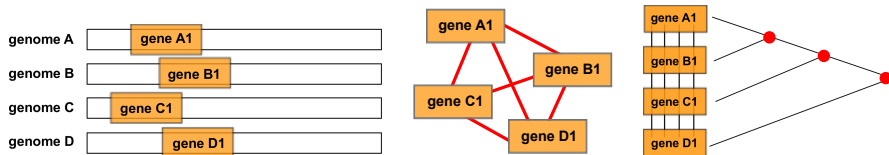
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# State-of-the-Art Tree Reconstruction



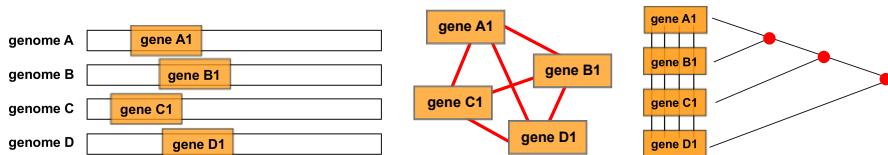
- Find 1:1-orthologs.
  - Paralogs = dangerous nuisance that has to be detected and removed.
  - Select families of genes that rarely exhibit duplications (e.g. rRNAs, ribosomal proteins)

# State-of-the-Art Tree Reconstruction



- Find 1:1-orthologs.
  - Paralogs = dangerous nuisance that has to be detected and removed.
  - Select families of genes that rarely exhibit duplications (e.g. rRNAs, ribosomal proteins)
- Alignments of protein or DNA sequences and standard techniques yield evolutionary history that is believed to be congruent to that of the respective species.

# State-of-the-Art Tree Reconstruction

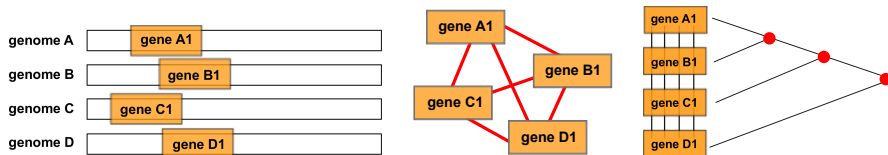


## Pitfalls:

- Information of evolutionary events as paralogs or xenologs is ignored, although they might contain valuable information about the evolutionary history of the species.
- The set of usable gene sets is strongly restricted ( $\leq 10\%$ ).



# State-of-the-Art Tree Reconstruction

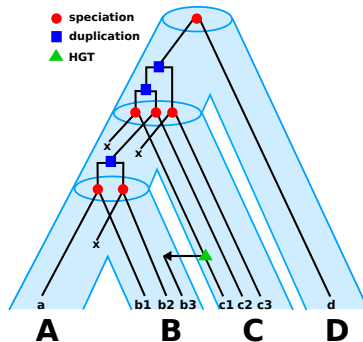


## Pitfalls:

- Information of evolutionary events as paralogs or xenologs is ignored, although they might contain valuable information about the evolutionary history of the species.
- The set of usable gene sets is strongly restricted ( $\leq 10\%$ ).

Thus, to get a better picture of the species evolution we try to include also the information of paralogs and xenologs.

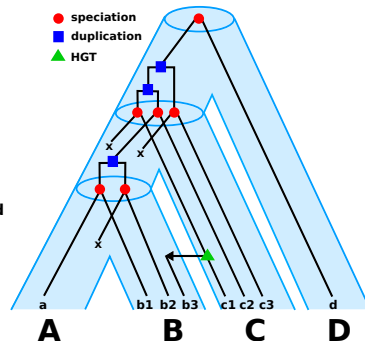
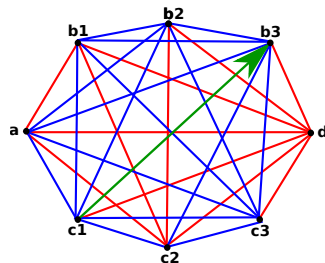
# Tree-Representable Sets of Binary Relations



An ordered pair  $(x, y)$  of two genes comprises

- orthologs if  $\text{lca}(x, y) = \bullet = \text{speciation}$
- paralogs if  $\text{lca}(x, y) = \blacksquare = \text{duplication}$
- xenologs if  $\text{lca}(x, y) = \blacktriangle = \text{HGT}$  and  $\blacktriangle$  “points from”  $x$  to  $y$  in  $T$

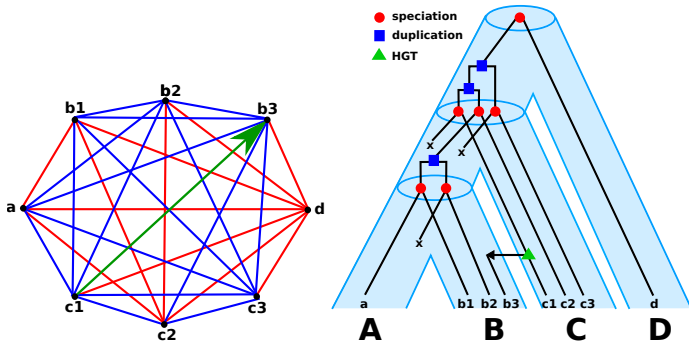
# Tree-Representable Sets of Binary Relations



The gene-tree determines three distinct relations

- $R_{\bullet}$ , the orthologs ( $\text{lca}(x, y) = \bullet$ )
- $R_{\blacksquare}$ , the paralogs ( $\text{lca}(x, y) = \blacksquare$ )
- $R_{\blacktriangle}$ , the xenologs ( $\text{lca}(x, y) = \blacktriangle$ ,  $\blacktriangle$  "points from"  $x$  to  $y$  in  $T$ )

# Tree-Representable Sets of Binary Relations



Orthologs, Paralog (and to some extent HGT) can be estimated **without** inferring a gene- or species trees.

Assume we have *estimated* binary relations  $R_1, \dots, R_k$  s.t.

$$(xy) \in R_i \text{ iff } \text{lca}(xy) = i \text{ in ordered tree } T$$

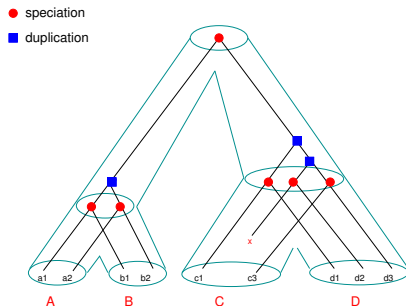
Thus, it is important to understand, when these estimates  $R_1, \dots, R_k$  can be “represented” in a single tree — thus, the edge-colored graph-representation.

## Sketch: Estimating $\Theta$ directly from the Data

- We know the assignment of genes to species and we can measure similarity  $s(x, y)$  of two genes using sequence alignments and `blast` bit scores
- $y \in B$  is a (putative) ortholog of  $x \in A$ , in symbols  $(x, y) \in \hat{\Theta}$ , if

1.  $A \neq B$ ,  
orthologs are never found in the same species

2.  $s(x,y) \approx \max_{x \in A, z \in B} s(x,z)$ ,  
if  $x$  and  $y$  are orthologs, then they do not have (much) closer relatives in the two species.



The relation  $\hat{\Theta}$  is only an estimate of a “correct” orthology relation:  
 $(x, y) \in \Theta$  iff  $t(x, y) = \bullet = \text{speciation}$

# Estimating $\Theta$ directly from the data

The relation  $\hat{\Theta}$  is only an estimate of a “correct” orthology relation  $\Theta$ .

**Aim:** Correct initial estimate  $\hat{\Theta}$  to the “closest” orthology relation  $\Theta$  that fits the data and build corresponding gene and species trees.

$\Rightarrow$  What is a “closest” orthology relation  $\Theta$ ?

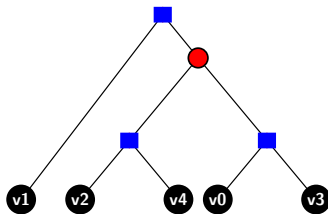
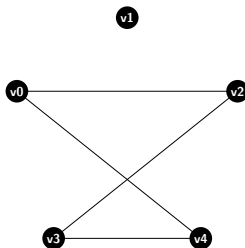
# Characterization of $\Theta$

**Question:** When does the initial estimate  $\hat{\Theta}$  fit the data?

**Equivalently we can ask for a "symbolic representation":**

For a given  $\hat{\Theta}$  when does there exist a tree  $T$  with event labeling  $t$  s.t.

- $t(\text{lca}(x, y)) = \bullet = \text{speciation}$  for all  $(x, y) \in \hat{\Theta}$  and
- $t(\text{lca}(x, y)) = \blacksquare = \text{duplication}$  for all  $(x, y) \notin \hat{\Theta}$ ?



$G_{\hat{\Theta}}$  with edge set  $\hat{\Theta} = \{(v0, v2), (v0, v4), (v2, v3), (v3, v4)\}$

## Characterization of $\hat{\Theta}$

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We used results by Böcker & Dress (1998) on “symbolic ultrametrics”:

### Theorem

*The following conditions are equivalent*

- *There is a symbolic representation for  $\hat{\Theta}$ .*
- **$G_{\hat{\Theta}}$  is a *Cograph*.**

---

Recovering Symbolically Dated, Rooted Trees from Symbolic Ultrametrics, Böcker & Dress, Adv. Math., 1998

Orthology Relations, Symbolic Ultrametrics, and Cographs, Hellmuth M, H.-Rosales M, Huber K, Moulton V, Stadler PF, Wieseke N, J. Math. Biol., 2012



# Cograph (=Complement reducible graph)

Corneil et al., 1981:

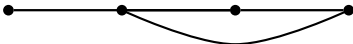
Cographs are defined recursively (Def. omitted)

$G$  is Cograph IFF  $G$  is “induced  $P_4$ -free”

Forbidden:



Allowed:



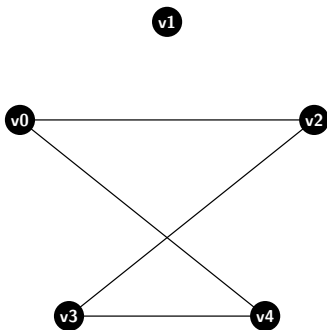
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**Every Cograph is associated with a unique Cotree.**



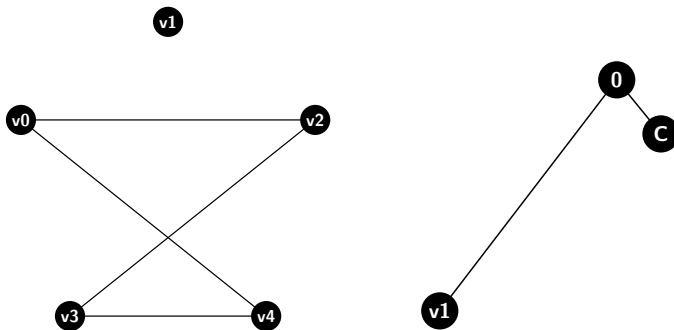
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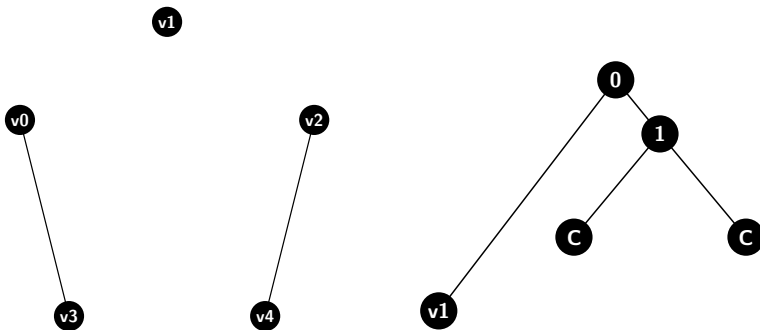
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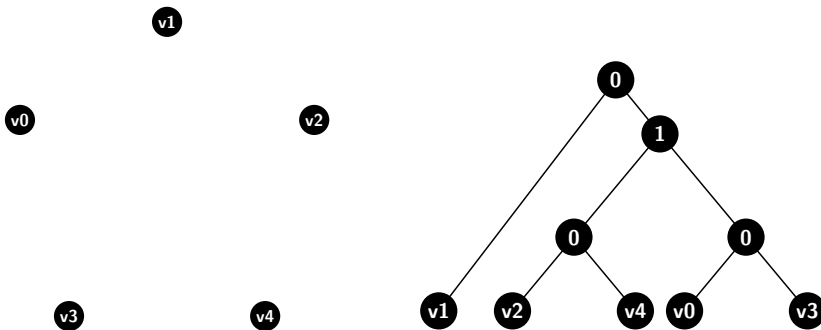
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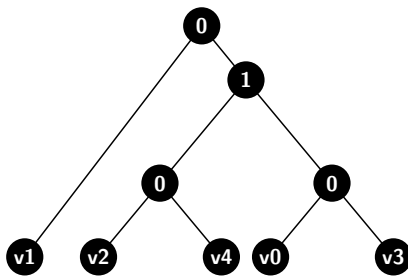
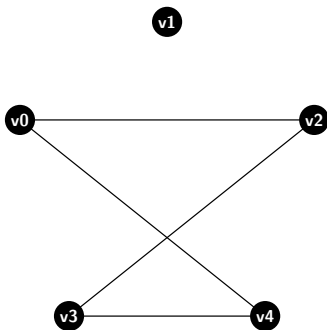
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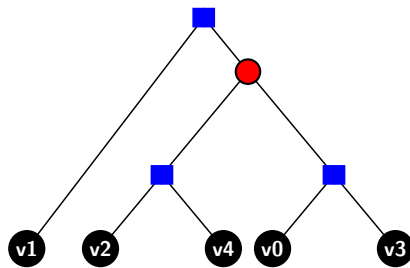
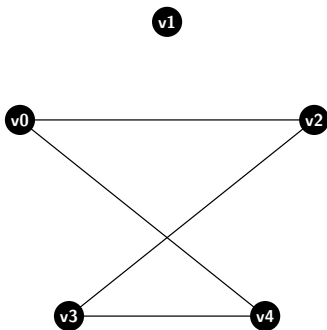
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$$(x, y) \in E(G) = \Theta \text{ if and only if } \text{lca}(x, y) = 1 = \bullet$$

## Characterization of $\Theta$

**Idea:** Correct the initial estimate  $\hat{\Theta}$  to the “closest” orthology relation  $\Theta$  that fits the data.

### Theorem

*There is a symbolic representation  $(T, t)$  for  $\hat{\Theta} \iff G_{\hat{\Theta}}$  is a Cograph.*

*There is a symbolic representation  $(T, t)$  for any symbolic relation (=colored graph  $G$ )  $\iff$  each monochromatic subgraph is a Cograph and on each triangle in  $G$  at most 2 colors are used.*



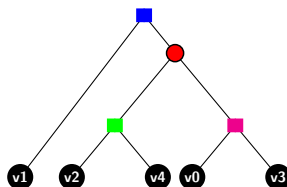
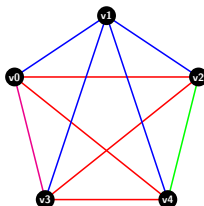
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# QUESTION

Assume we have a valid orthology relation.

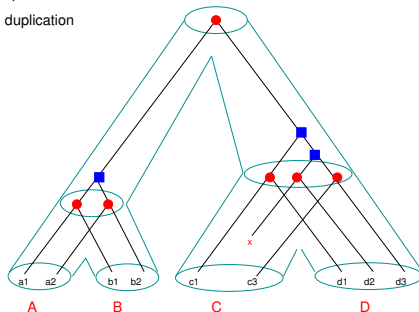
Therefore, we obtain an event-labeled gene tree.

**How can we infer the species tree?**

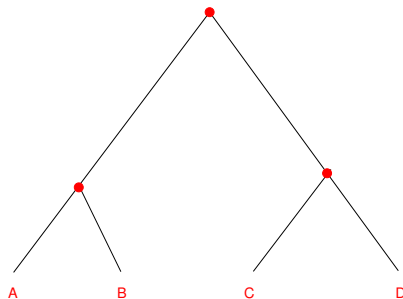
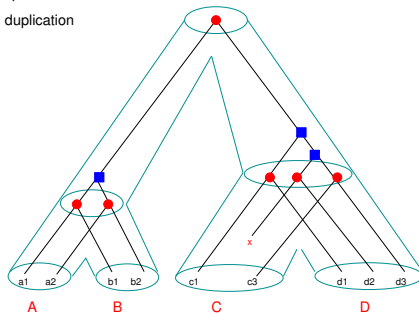
# Finding the species trees

● speciation

■ duplication

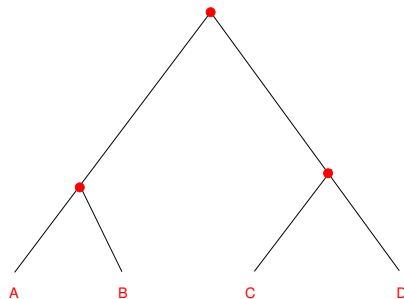
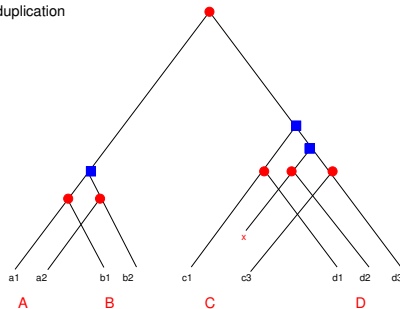


- speciation
- duplication



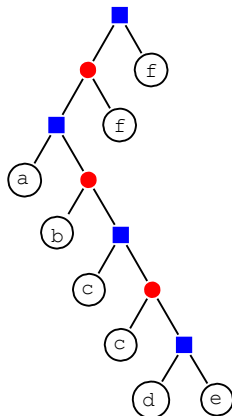
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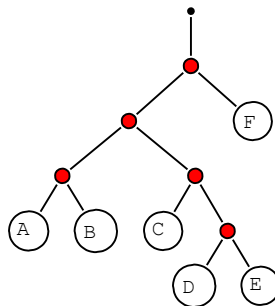


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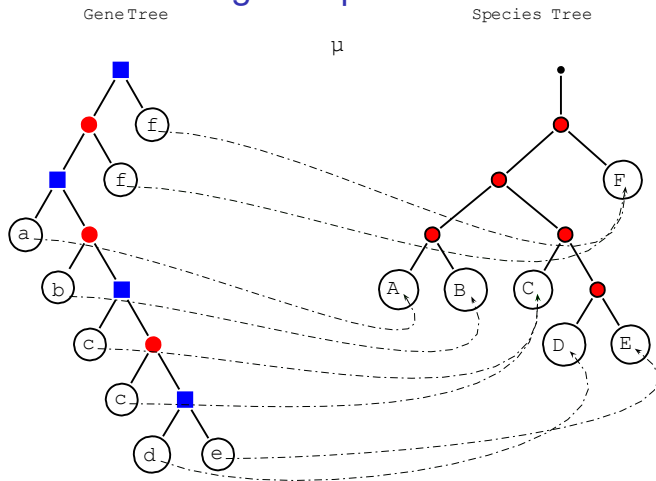
Gene Tree



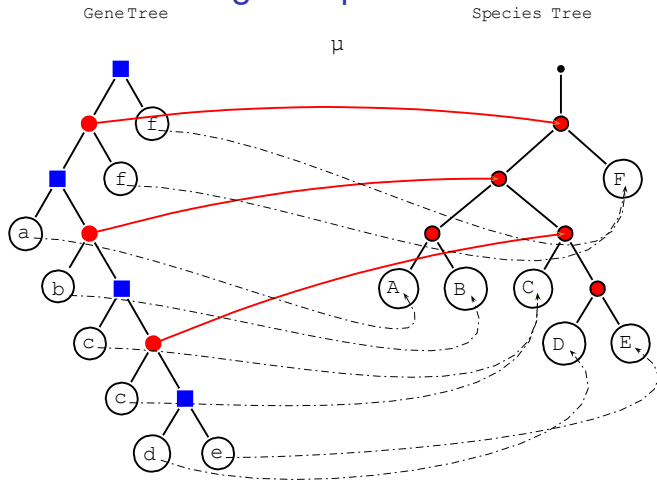
Species Tree

 $\mu$

# Finding the species trees



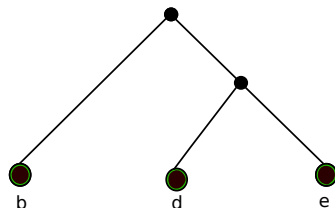
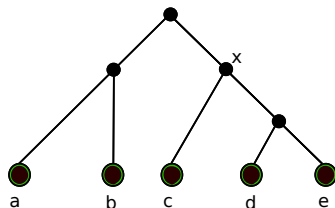
# Finding the species trees







# Trees and triples



For three leaves  $a, b, c$  in  $T$  we write  $ab|c$  if the path from  $a$  to  $b$  does not intersect the path from  $c$  to the root.

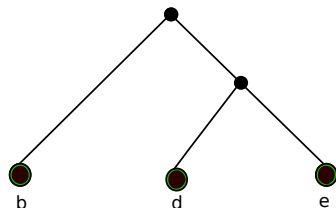
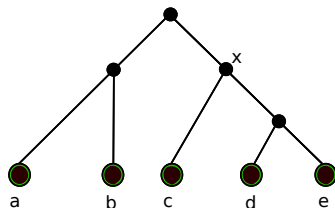
## Right Tree:

$$\mathcal{R}(T) = \{de|b\}$$

## Left Tree:

$$\mathcal{R}(T) = \{ab|c, ab|d, ab|e, de|a, de|b, de|c, cd|a, cd|b, ce|a, ce|b\}$$

# Trees and triples



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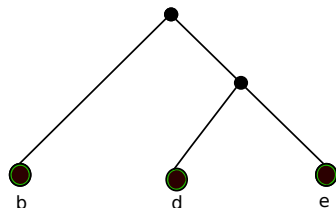
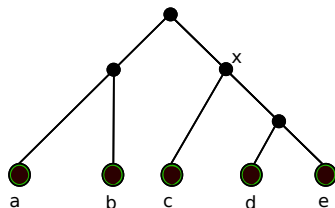
**Left Tree:**

$$\mathcal{R}(T) = \{ab|c, ab|d, ab|e, de|a, de|b, de|c, cd|a, cd|b, ce|a, ce|b\}$$

An arbitrary set of triples  $\mathcal{R}$  is **consistent**,  
if there is a tree that displays all triples in  $\mathcal{R}$

Exmpl:  $\mathcal{R}(T)$  is consistent.  $\mathcal{R}(T) \cup \{eb|d\}$  is not consistent.

# Trees and triples



For three leaves  $a, b, c$  in  $T$  we write  $ab|c$  if the path from  $a$  to  $b$  does not intersect the path from  $c$  to the root.

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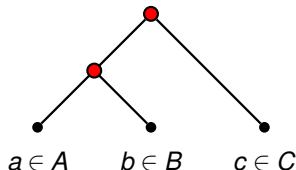
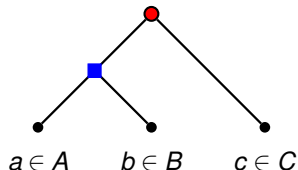
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**Theorem** [Aho, Sagiv, Szymanski, Ullman - 1981, Semple & Steel - 2003]

There is a polynomial time algorithm – called BUILD – that constructs a tree for a given set of triples  $\mathcal{R}$  or recognizes  $\mathcal{R}$  as inconsistent.

# Triples for inferring the species tree



Given an event-labeled gene tree  $(T, t)$  and  $ab|c \in \mathcal{R}(T)$ .

We write  $ab|c^\bullet$  if

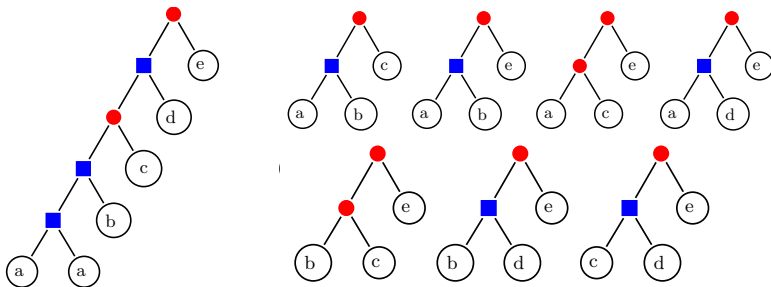
$$t(\text{lca}(a, b, c)) = \bullet = \text{"speciation"}$$

We know the assignment of genes to the species in which they occur.  
This gives us the triple set:

$$\mathbb{S} = \{(AB|C : \exists ab|c^\bullet \text{ with } a \in A, b \in B, c \in C)\}$$

# Triples for inferring the species tree

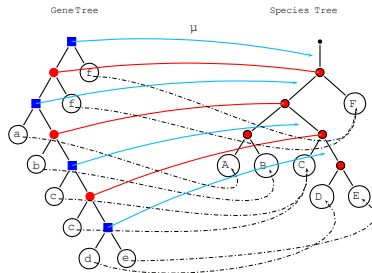
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$$\mathbb{S} = \{AB|C, AB|E, AC|E, AD|E, BC|E, BD|E, CD|E\}$$

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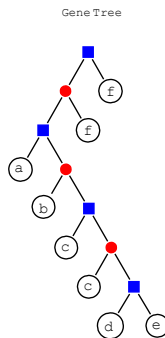
## Theorem

There is a species tree for the gene tree  $(T, t)$ , i.e., for the symbolic representation of  $\Theta \iff$  the triple set  $\mathbb{S}$  is consistent.

A reconciliation map  $\mu$  from  $(T, t)$  to the species tree  $S$  can be constructed in polynomial time.

# Inferring the Species Tree in $O(|\mathcal{G}||\mathcal{S}|)$ time

**Given:** Gene tree  $(T, t) = ((V, E), t)$ ,    Gene set  $\mathcal{G} \subseteq V$   
Consistent triple set  $\mathcal{S}$                       Species set  $\mathcal{G}$   
map  $\sigma : \mathcal{G} \rightarrow \mathcal{G}$  from genes to its respective species.

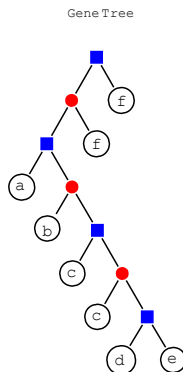
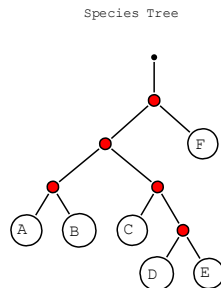




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 map  $\sigma : \mathcal{G} \rightarrow \mathcal{S}$  from genes to its respective species.

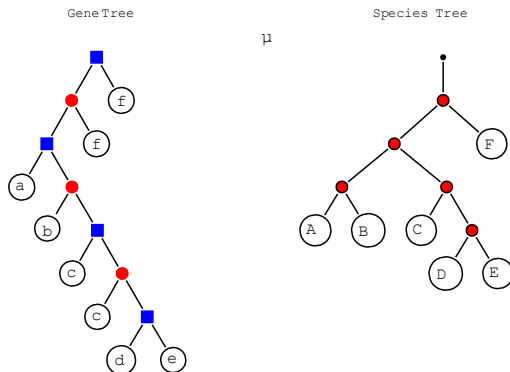
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 $\mu$ 


# Inferring the Species Tree in $O(|\mathcal{G}||\mathcal{S}|)$ time

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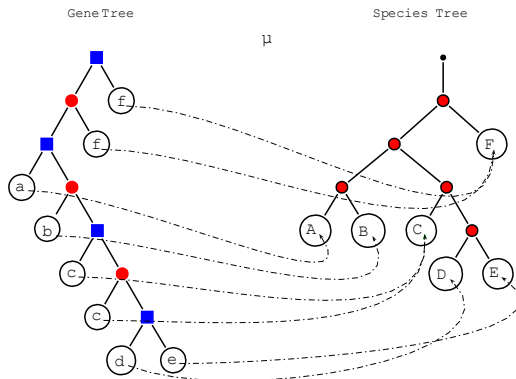


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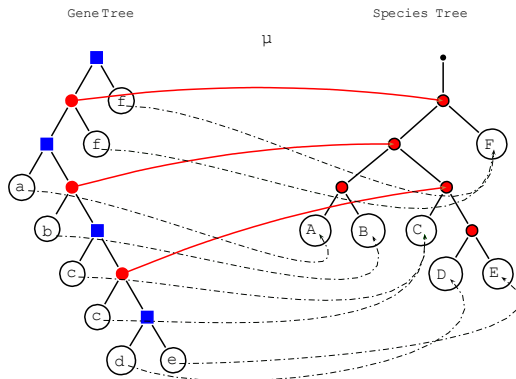


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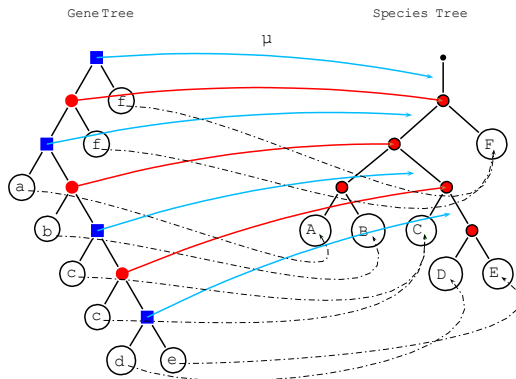


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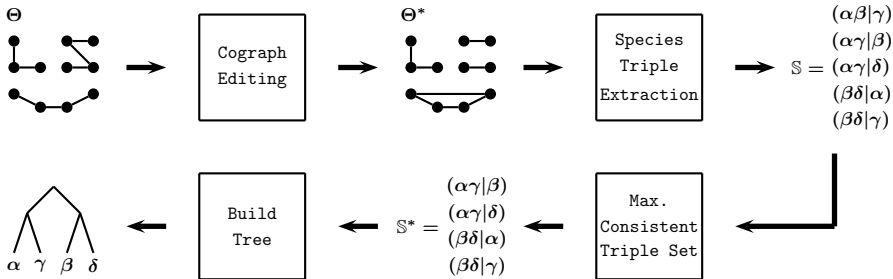
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- $\mu(x) = [u, \text{lca}_S(\sigma(L(x)))]$  if  $t(x) = \blacksquare = \text{duplication}$



# Workflow ParaPhylo

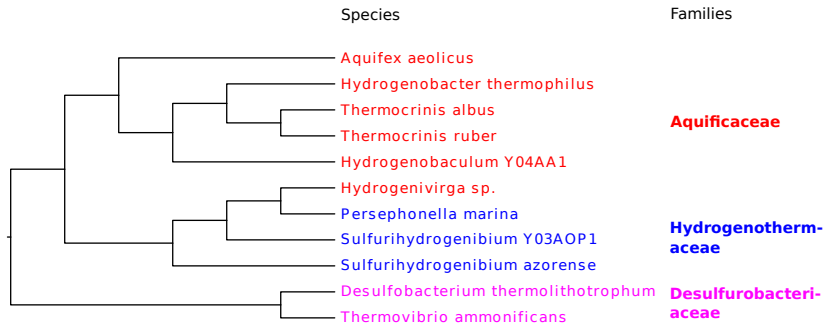
Given a binary relation  $\Theta$  comprising e.g. the estimated orthologs or paralogs.



We formulated all NP-hard problems (CE, MCT, LRT) as Integer Linear Program (ILP):

$$\min F(x) \text{ s.t. } Ax \leq b$$

# Results - Real Life Data



- Class of bacteria that live in harsh environmental settings, e.g., hot springs, sulfur pools, and thermal ocean vents.
- 11 Aquificales species with 2887 gene families (1372 - 3809 genes per species)
- ProteinOrtho → ILP-pipeline (CE→MCS→LRT).

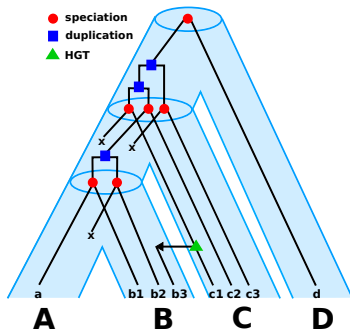
# Results: Simulation

Artificial data generated with ALF:

## Simulation of “true” evol. history

- generate binary species tree
- simulate dupl./loss/HGT history of gene sequences (within species tree)

**Output:** Species tree with embedded gene trees and gene-sequences





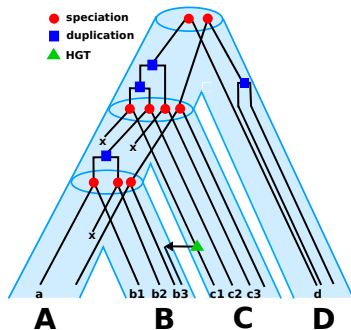
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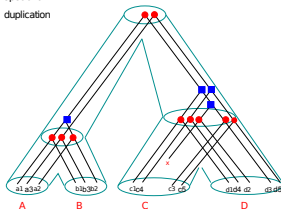


## Results - Simulation without HGT

ALF (no HGT)

● speciation

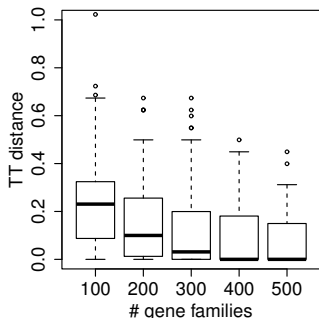
■ duplication



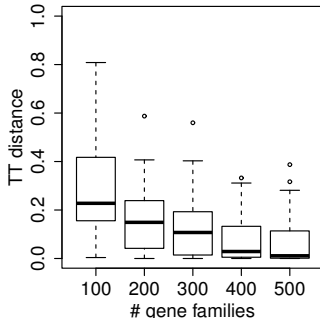
- The cograph  $G_{\Theta}$  is directly accessible
- Compute cotree of  $G_{\Theta}$
- Extract the species triples set  $\mathbb{S}$  (consistent)
- Compute least resolved species tree and compare it with initial species tree

## Results - Simulation without HGT

Accuracy of reconstructed species trees as function of number of independent gene families:



10 species



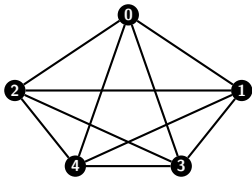
20 species

Simulation with ALF with duplication/loss rate 0.005 (~ 8% duplications) and no HGT.

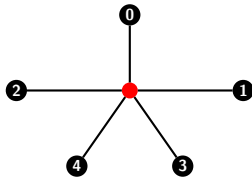
TT distance  $\hat{=}$  “num different triples in initial and reconstructed species tree”

## Phylogenomics with Paralogs

In our model:  $(x, y) \notin \Theta$  iff the distinct genes  $x$  and  $y$  are paralogs



$G_{\Theta}$



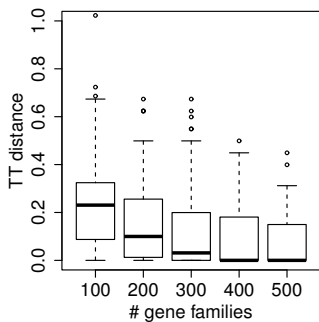
$(T, t)$

If  $\nexists$  paralogs  $\rightarrow G_{\Theta}$  is a clique  $\rightarrow$  gene tree is a star  $\rightarrow$  no species triples can be inferred.

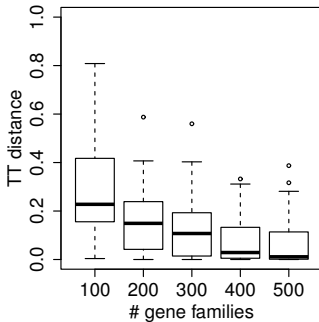
To obtain fully resolved species trees, a sufficient number of gene duplications must have occurred, since the **phylogenetic information** utilized by our approach **is entirely contained in the duplication events**.

## Results - Simulation without HGT

Accuracy of reconstructed species trees as function of number of independent gene families:



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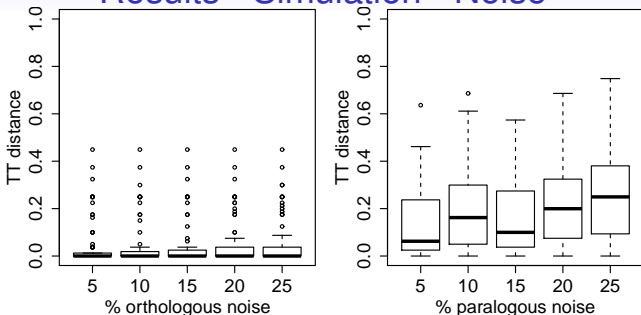


20 species

Average TT distance always smaller than 0.09 for more than 300 gene families, independent from the number of species.

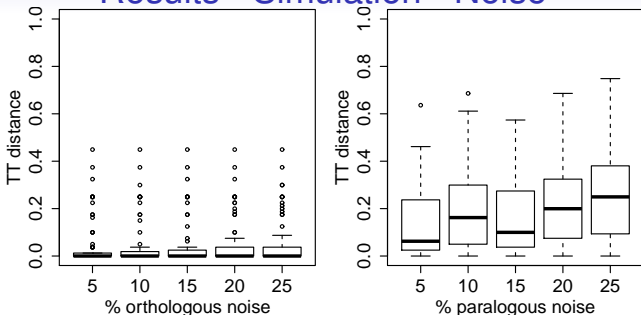
Deviations from perfect reconstructions are exclusively explained by a lack of perfect resolution.

## Results - Simulation - Noise



- ALF (10 species and 1000 gene families) -  $G_{\Theta}$  as before - add noise - start ILP-pipeline (CE $\rightarrow$ MCS $\rightarrow$ LRT).
- orthologous noise (overpredicting): flip paralogs with prob.  $p$
- paralogous noise (underpredicting): flip orthologs with prob.  $p$
- $p \in [0.05, 0.25]$

## Results - Simulation - Noise



**orthologous noise:** additional edges in  $G_{\Theta}$

- $G_{\Theta}$  becomes more clique-like
- less species triples can be inferred and thus, **less wrong** species triples

**paralogous noise:** remove edges from  $G_{\Theta}$

- $G_{\Theta}$  becomes less clique-like
- more species triples can be inferred and thus, **more wrong** species triples

## Results - Runtime

**Table :** Running time in seconds on 2 Six-Core AMD Opteron™ Processors with 2.6GHz for individual sub-tasks: **CE** cognograph editing, **MCS** maximal consistent subset of triples, **LRT** least resolved tree.

<b>Data</b>	<b>CE</b>	<b>MCS</b>	<b>LRT</b>	<b>Total<sup>a</sup></b>
Simulations <sup>b</sup>	125 <sup>c</sup>	< 1	< 1 <sup>d</sup>	126
<i>Aquificales</i> <sup>e</sup>	34	< 1	< 1 (6) <sup>g</sup>	34
<i>Enterobacteriales</i> <sup>f</sup>	2673	2	< 1 (1749) <sup>g</sup>	2676

<sup>a</sup> Total time includes triple extraction, parsing input, and writing output files.

<sup>b</sup> Average of 2000 simulations with *ALF*, 10 species, 1000 gene families.

100 runs for each 4 noise models with different  $p \in \{0.05, 0.1, 0.15, 0.2, 0.25\}$

<sup>c</sup> 2,000,000 cognographs, 41 not optimally solved within time limit of 30 min.

<sup>d</sup> In 95.95% of the simulations the LRT could be found using *BUILD*.

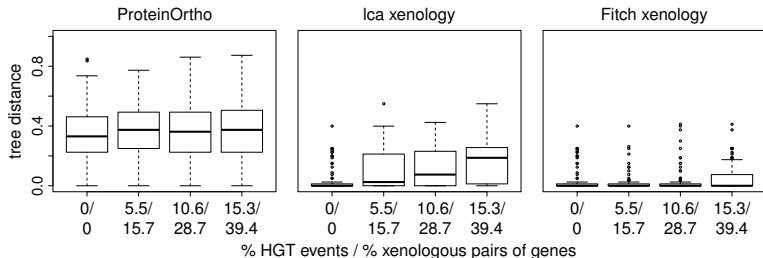
<sup>e</sup> 11 *Aquificales* species with 2887 gene families.

<sup>f</sup> 19 *Enterobacteriales* species with 8308 gene families.

<sup>g</sup> A unique tree was obtained using *BUILD*. Second value indicates running time with ILP solving enforced.



# Results - HGT



left  $\Theta$  = “estim.” orthologs via ProteinOrtho

middle  $\Theta$  = orthologs + lca-xenologs

*(orthology-overprediction / all paralogs are correctly identified)*

right  $\Theta$  = orthologs + all pairs of genes having at least one  
HGT event on their path

*(orthology-overprediction / all paralogs that are not disturbed by HGT on their paths are correctly identified)*

---

<sup>0</sup> **ProteinOrtho: Detection of (Co)orthologs in large-scale analysis.**, Lechner M, Findeiß S, Steiner L, Marz M, Stadler PF, Prohaska SJ, *BMC Bioinformatics*, 2011

**Phylogenomics with Paralogs**, Hellmuth M, Wieseke N, Lechner M, Lenhof HP, Middendorf M, Stadler PF, *PNAS*, 2015

# Summary of the Results

## Results:

- We don't need to restrict the dataset to 1:1 orthologs!
- More genefamilies (*incl. paralogs*) → more accurate species trees.
- Don't worry too much about HGT.
- accurate species trees from real data for up to 20 species with ~10000 gene families

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- accurate species trees from real data for up to 20 species with ~10000 gene families

## Open Problems and TODO's:

- More accurate orthology prediction methods are needed, or even methods to predict paralogs and xenologs.
- ILP allows to compute *exact* solutions for the NP-hard problems, however, for larger species sets the runtime dramatically increases  
→ We need reliable and efficient heuristics.