ICASSP

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VisionLab

## Color Constancy

The perceived color remains constant regardless of the color of the light source

- Performed unconsciously by the human visual system - Machine vision systems have difficulty to perform such tasks


## Aim of Color Constancy

To estimate the color vector of the light source $\mathbf{L}$ Obtain a canonical image from a color casted scene

$$
\begin{aligned}
I(x, y) & =\int R(x, y, \lambda) E(x, y, \lambda) S(\lambda) d \lambda \\
L(x, y, \lambda) & =\int E(x, y, \lambda) S(\lambda) d \lambda
\end{aligned}
$$

- We cannot be sure about;
- The type of the light source - The type of the capturing device
$\qquad$ Pixel position $\qquad$ Observations
$\begin{array}{lllll} & x, y: & \text { Pixel position } & R: & \text { Reflectance } \quad E: \\ \text { Wavelength source } \\ & S: & \text { Sensor characteristics of the camera }\end{array}$
- Human visual system might be estimating the illuminant of a scene based on;
$\checkmark$ Space-average color $\checkmark$ Highest luminance patch
- Color constancy studies based on our visual system are effective $\checkmark$ Gray World
$\checkmark$ maxRGB


## Motivation and Aim of the Study

Not every pixel is informative for color constancy To improve our method with a simple yet effective approach $\checkmark$ We reduce the impact of non-informative pixels

- To analyze whether our strategy is effective for other color constancy studies



## Assumption

1. The world is gray, on average
2. There are bright pixels somewhere in the scene

Main Idea
$\checkmark$ If there is a shift from the gray world, it should be caused by the illumination condition of the scene


Proposed Method


1. Linearize the image
2. Clip the saturated pixels
3. Determine the salient pixels, i.e. whitest pixels
4. For each block containing salient pixels, find two informative elements;

$$
\text { - The bright pixel, } I_{p, \max }=\left[R_{p, \max }, G_{p, \max }, B_{p, \max }\right]
$$

- The unique achromatic value, i.e. gray value, $\mu_{p}$

5. Find the deviation of $I_{p, \max }$ from $\mu_{p}$ by using a scaling vector $\mathbf{C}_{p}=\left[c_{r} c_{g} c_{b}\right]$;

$$
\mathbf{C}_{\mathbf{p}}=\underset{\mathbf{C}_{\mathbf{p}}}{\arg \min }\left\|I_{p, \max } \mathbf{C}_{\mathbf{p}}-\mu_{p}\right\|_{2} \quad \text { with } \quad \forall c \in \mathbf{C}_{\mathbf{p}}: c \geq 0
$$

6. Find the estimate of the global illuminant;

$$
\mathbf{L}_{e s t}=\sum_{p=1}^{n} \frac{\mathbf{C}_{p}}{n}
$$

$$
n \text { : number of blocks }
$$

Investigation of the Block Size

|  | Investigation of the Block Size |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | INTEL-TAU Random Set |  |  |  |  |  |  |  |  |
|  | $\mathbf{8 \times 8}$ | $\mathbf{1 6} \times \mathbf{1 6}$ | $\mathbf{3 2} \times \mathbf{3 2}$ | $\mathbf{6 4} \times \mathbf{6 4}$ | $\mathbf{1 2 8} \times \mathbf{1 2 8}$ | $\mathbf{3 0 0} \times \mathbf{3 0 0}$ | $\mathbf{6 0 0} \times \mathbf{6 0 0}$ |  |  |
| Mean Angular Error | 3.759 | 3.747 | 3.733 | 3.729 | $\mathbf{3 . 7 2 5}$ | 3.733 | 3.783 |  |  |
|  | RECommended ColorChecker Random Set |  |  |  |  |  |  |  |  |
|  | $\mathbf{8 \times 8}$ | $\mathbf{1 6} \times \mathbf{1 6}$ | $\mathbf{3 2} \times \mathbf{3 2}$ | $\mathbf{6 4} \times \mathbf{6 4}$ | $\mathbf{1 2 8} \times \mathbf{1 2 8}$ | $\mathbf{3 0 0} \times \mathbf{3 0 0}$ | $\mathbf{6 0 0} \times \mathbf{6 0 0}$ |  |  |
| Mean Angular Error | 3.630 | 3.603 | 3.571 | 3.542 | 3.518 | $\mathbf{3 . 4 9 2}$ | 3.607 |  |  |

- The block sizes are experimentally determined by investigating the relationship between the mean angular error and different kernel sizes


Summary

- We recently proposed a learning-free algorithm relying on the assumptions

$$
\checkmark \text { Gray world } \quad \checkmark \operatorname{maxRBG}
$$

We modified our algorithm by only considering the patches containing the

## salient pixels

$$
\checkmark \text { Pixels closest to white }
$$

We showed that applying our strategy to some other methods improves their effectiveness
$\checkmark$ Block-based approach $\quad \checkmark$ Considering only the salient pixels

